

## Plug-in Signal Conditioners M-UNIT

### ENCODER SPEED TRANSMITTER

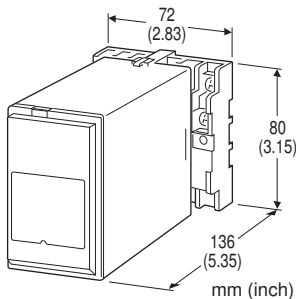
(field-programmable; built-in excitation)

#### Functions & Features

- Converts a two-phase forward and reverse rotation pulse signal with 90 degree phase difference into a forward and reverse speed signal
- Built-in excitation
- Field-selectable input type and range
- Isolation up to 2000 V AC
- High-density mounting

#### Typical Applications

- Measuring moving speed of a machine with a rotary encoder



## MODEL: JRP2-[1][2]-[3][4]

### ORDERING INFORMATION

- Code number: JRP2-[1][2]-[3][4]
- Specify a code from below for each [1] through [4]. (e.g. JRP2-76-K/Q)
- Specify the specification for option code /Q (e.g. /C01/S01)
- Special output range (For codes Z & 0)
- Use Ordering Information Sheet (No. ESU-1577). Factory setting (indicated below) will be used if not otherwise specified.

#### Factory Setting

Input type	Open collector
Pulse amplitude	----
Pulse sensing	DC coupled
Noise filter	Low
Detecting level	1V*1 (5V excitation) 2V*1 (12/24V excitation)
Frequency range	0 – 1 kHz
Input zero frequency	0 Hz
Input span frequency	1 kHz
Low-end cutout	0 Hz
Low-end cutout deadband	0.01kHz
Alarm setpoint	100%
Alarm deadband	1.00%
Alarm mode	High alarm
Linearization	Without

\*1. Detecting voltage in the internal circuit

### INPUT - Field-selectable

Open collector

Voltage pulse

RS-422 line driver pulse

Two inputs (phase A and B) are required for adequate operation of the this unit.

### [1] EXCITATION

- 1: 5 V DC @ 120 mA
- 4: 12 V DC @ 60 mA
- 7: 24 V DC @ 25 mA

### [2] OUTPUT

#### Current

- A: 4 – 20 mA DC (Load resistance 750 Ω max.)
- B: 2 – 10 mA DC (Load resistance 1500 Ω max.)
- C: 1 – 5 mA DC (Load resistance 3000 Ω max.)
- D: 0 – 20 mA DC (Load resistance 750 Ω max.)
- E: 0 – 16 mA DC (Load resistance 900 Ω max.)
- F: 0 – 10 mA DC (Load resistance 1500 Ω max.)
- G: 0 – 1 mA DC (Load resistance 15 kΩ max.)
- Z: Specify current (See OUTPUT SPECIFICATIONS)

#### Voltage

- 1: 0 – 10 mV DC (Load resistance 10 kΩ min.)
- 2: 0 – 100 mV DC (Load resistance 100 kΩ min.)
- 3: 0 – 1 V DC (Load resistance 100 Ω min.)
- 4: 0 – 10 V DC (Load resistance 1000 Ω min.)
- 5: 0 – 5 V DC (Load resistance 500 Ω min.)
- 6: 1 – 5 V DC (Load resistance 500 Ω min.)
- 4W: -10 – +10 V DC (Load resistance 2000 Ω min.)
- 5W: -5 – +5 V DC (Load resistance 1000 Ω min.)
- 0: Specify voltage (See OUTPUT SPECIFICATIONS)



**[3] POWER INPUT****AC Power**

K: 85 - 132 V AC

**DC Power**

S: 12 V DC

R: 24 V DC

V: 48 V DC

P: 110 V DC

**[4] OPTIONS**

blank: none

/Q: With options (specify the specification)

**SPECIFICATIONS OF OPTION: Q (multiple selections)****COATING (For the detail, refer to M-System's web site.)**

/C01: Silicone coating

/C02: Polyurethane coating

/C03: Rubber coating

**TERMINAL SCREW MATERIAL**

/S01: Stainless steel

**RELATED PRODUCTS**

- JX configurator connection kit (model: JXCON)
- Programming Unit (model: PU-2x)

**GENERAL SPECIFICATIONS****Construction:** Plug-in**Connection:** M3.5 screw terminals**Screw terminal:** Chromated steel (standard) or stainless steel**Housing material:** Flame-resistant resin (black)**Isolation:** Input to DC output to alarm output to power**Overrange output:** Approx. -15 to +115 % at 1 - 5 V**Zero adjustment:** -5 to +5 % (front)**Span adjustment:** 95 to 105 % (front)**Alarm mode:** High or Low**Alarm setpoint:** -15 - +115 %**Alarm deadband:** 0 - 20 %**Input monitor (PL1):** Red LED blinks according to the input phase A.**Input monitor (PL2):** Red LED blinks according to the input phase B.**Excitation adjustment:** 5 - 24 V DC**Software programming:** Programming unit (model: PU-2x) used to set the input frequency range, zero and span, low-end cutout, alarm, fine output adj., linearization, etc. (Refer to the users manual of JXCON for the adjustments configurable with JXCON.)**Adjustments:** With DIP and Rotary switches.

- Input Type

- Noise Filter
- Pulse amplitude

(Refer to the instruction manual for details)

**Modular jack:** Connecting the PU-2x**Low-end cutout:** Specify frequency (When the low-end cutout is set to 0 Hz, the deadband is not valid.)**INPUT SPECIFICATIONS****Excitation:** Shortcircuit protection; approx. 440 mA (max.) at shortcircuit**Maximum frequency:** 200 kHz**Frequency ranges:** 0 - 0.01 Hz through 100 kHz

Note: Choose 100 kHz range to set the zero/span frequencies greater than 100 kHz.

**Minimum span:** 10 % of the selected frequency range**Minimum pulse width time requirement:** 2.5  $\mu$ sec. for both ON and OFF**■ Open Collector****Input requirements (Excitation: Sensing)**

5 V: Approx. 4 V / 1.0 mA

12 V: Approx. 9 V / 2.3 mA

24 V: Approx. 16 V / 4.7 mA

**ON resistance:**  $\leq$  200  $\Omega$ **OFF resistance:**  $\geq$  200 k $\Omega$ **Detecting level:**

1 V (5 V excitation)

2 V (12/24 V excitation)

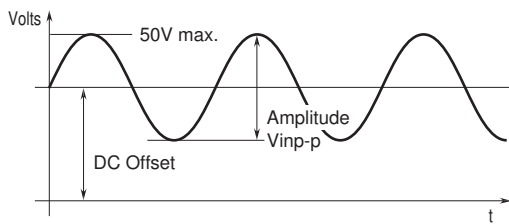
(Detecting voltage in the internal circuit. For open collector input, be sure to re-adjust the voltage back to 1 V (5 V excitation) or 2 V (12/24 V excitation) if it has been changed for other input types.)

**Detecting pulse edge:** OFF (input monitor LED ON) to ON (LED OFF)**■ Voltage Pulse****Waveform:** Square or sine**Input impedance:** 10 k $\Omega$  min.**Pulse amplitude:** 0.1 - 100 Vp-p**Max. voltage between input terminals:** 50 V**Detecting level:** 0 - 5 V (factory setting: 2 V)

(Detecting voltage in the internal circuit.)

**Detecting pulse state:** A pulse rise detected when the input voltage goes above the detecting level (input monitor LED ON); a pulse sink detected when it goes below the level (LED OFF).**■ RS-422 Line Driver Pulse****Receiver:** Conforms to RS-422

## Voltage pulse waveform



**Alarm setpoint accuracy:**  $\pm 0.1\%$

**Temp. coefficient:**  $\pm 0.015\%/^{\circ}\text{C}$  ( $\pm 0.008\%/^{\circ}\text{F}$ )

**Response time (0 - 90 %)**

$\leq 1$  Hz range: two pulse cycles

$\geq 10$  Hz range: 0.5 sec. + one pulse cycle

**Line voltage effect:**  $\pm 0.1\%$  over voltage range

**Insulation resistance:**  $\geq 100\ \text{M}\Omega$  with 500 V DC

**Dielectric strength:**

2000 V AC @ 1 minute (input to DC output to power)

1500 V AC @ 1 minute (input or DC output or power to alarm output)

2000 V AC @ 1 minute (circuit to ground)

## OUTPUT SPECIFICATIONS

■ **DC Current:** 0 - 20 mA DC

**Minimum span:** 1 mA

**Offset:** Max. 1.5 times span

**Load resistance:** Output drive 15 V max.

■ **DC Voltage:** -10 - +12 V DC

**Minimum span:** 5 mV

**Offset:** Max. 1.5 times span

**Load resistance:** Output drive 10 mA max.; 5 mA for negative voltage output; at  $\geq 0.5\ \text{V}$

■ **Alarm Output:** Relay contact

**Rated load:** 125 V AC @ 0.5 A ( $\cos \theta = 1$ )

30 V DC @ 0.5 A (resistive load)

**Maximum switching voltage:** 250 V AC or 125 V DC

**Maximum switching power:** 62.5 VA or 60 W

**Minimum load:** 10 mV DC @ 1 mA

**Mechanical life:**  $5 \times 10^7$  cycles (300 cycles/minute)

For maximum relay life with inductive loads, external protection is recommended.

## INSTALLATION

**Power input**

• **AC:** Operational voltage range 85 - 132 V, 47 - 66 Hz, approx. 7 VA

• **DC:** Operational voltage range: Rating  $\pm 10\%$ , or 85 - 150 V for 110 V rating; ripple 10 %p-p max.; Approx. 4 W (140 mA at 24 V)

**Operating temperature:** -5 to  $+60^{\circ}\text{C}$  (23 to  $140^{\circ}\text{F}$ )

**Operating humidity:** 30 to 90 %RH (non-condensing)

**Mounting:** Surface or DIN rail

**Weight:** 350 g (0.77 lb)

## PERFORMANCE in percentage of span

**Accuracy:** Input accuracy + output accuracy

**Output accuracy:**  $\pm 0.05\%$  of the output range

**Input accuracy:**  $\pm 0.05\%$  of the selected freq. range

The input accuracy is inversely proportional to the input span, except fixed to  $\pm 0.05\%$  with  $[\text{Freq. Range} \div \text{Span}] \leq 1$ .

[Example] Open collector input, 0 - 50 kHz

Selected Freq. Range (100 kHz)  $\div$  Input Span (50 kHz)  $\times$

Accuracy 0.05 % + Output Accuracy 0.05 % =  $\pm 0.15\%$



**幸託有限公司**  
XIN TOP CORPORATION

TEL : (02)2598-1199

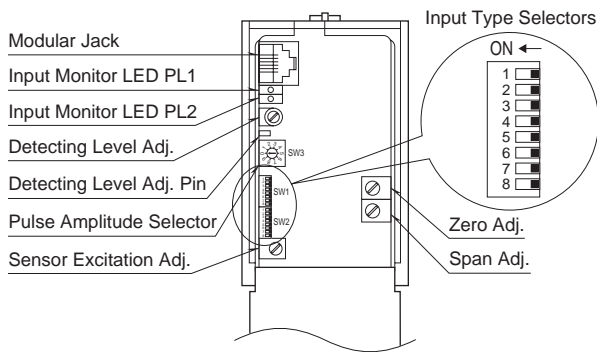
FAX : (02)2596-2331

E-mail : info@xintop.com

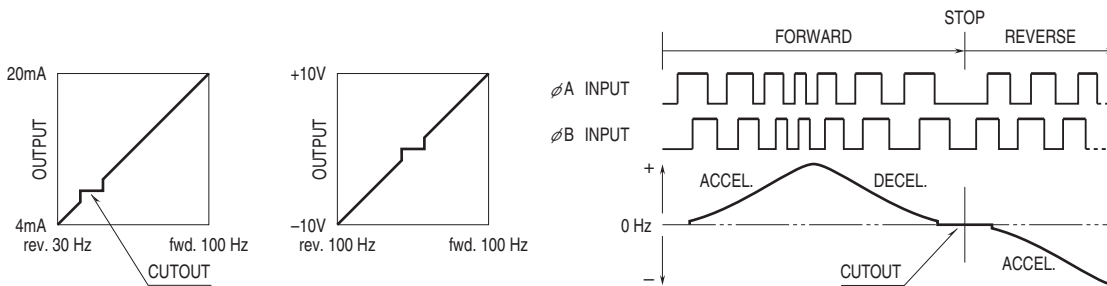
Website : www.xintop.com

## EXTERNAL VIEW

Refer to the instruction manual for the setting procedure.

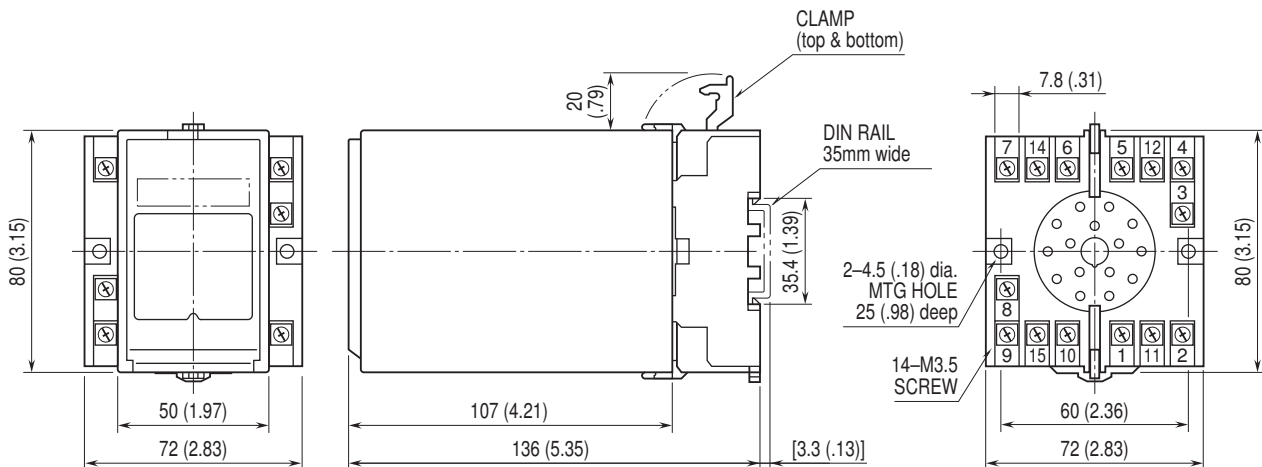


## OPERATION



Forward Rotation: Phase A leads the Phase B by 90 degrees.  
 Reverse Rotation: Phase A lags behind Phase B by 90 degrees.

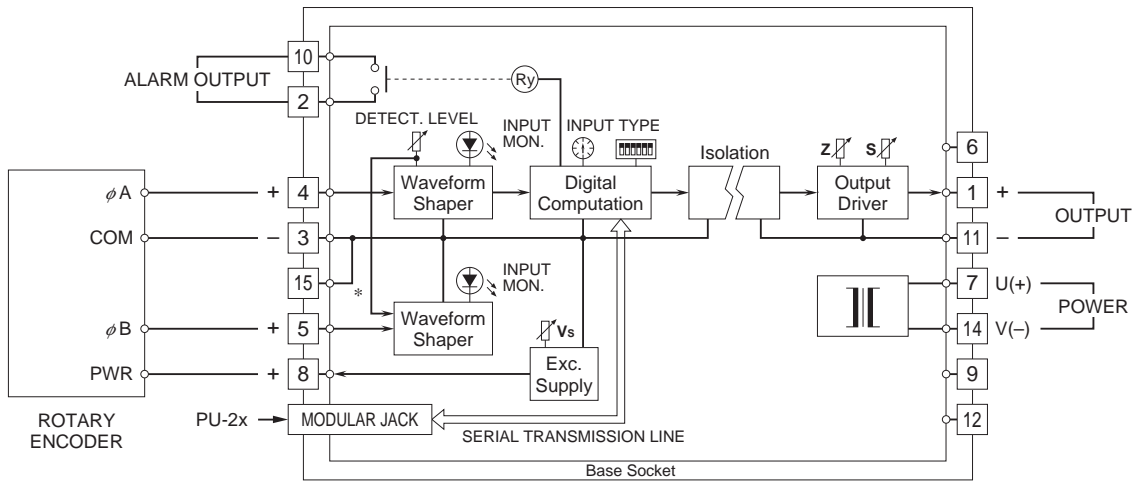
## EXTERNAL DIMENSIONS & TERMINAL ASSIGNMENTS unit: mm (inch)



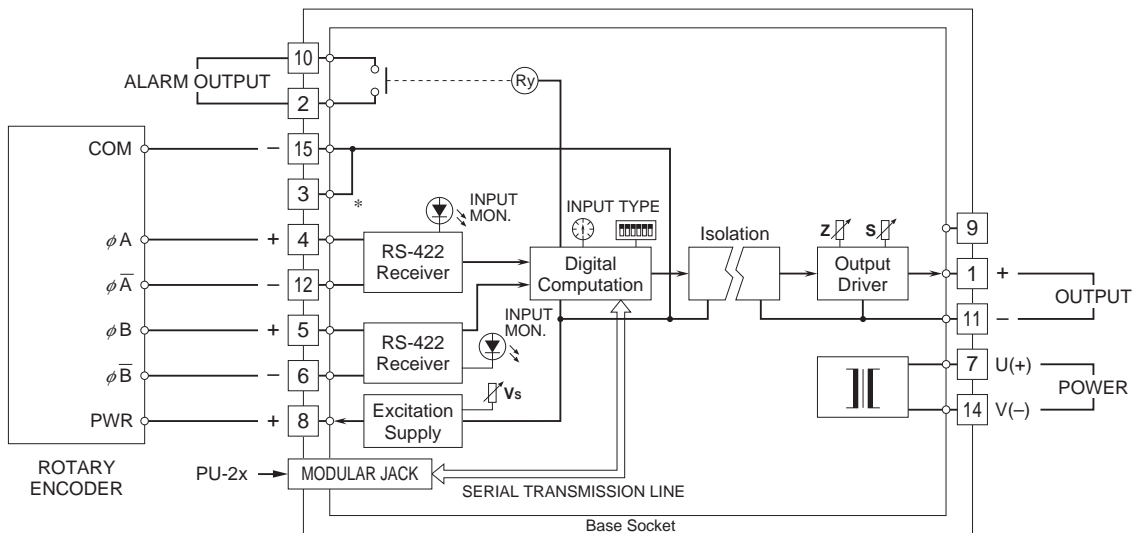
• When mounting, no extra space is needed between units.

**SCHEMATIC CIRCUITRY & CONNECTION DIAGRAM**

■ OPEN COLLECTOR or VOLTAGE PULSE INPUT



■ RS-422 LINE DRIVER INPUT



\*Terminals 3 and 15 are internally connected.  
The rotary encoder's COM terminal can be connected to either one.



Specifications are subject to change without notice.

